

## Operating Instructions Control Units Type TC11, TC15, TC16

### Installation (only for authorized personnel)

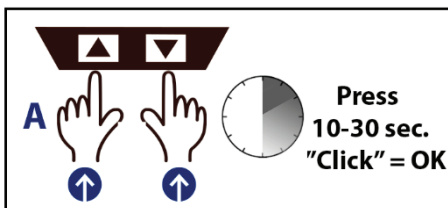
- Plug in the drives into the 8-pin molex sockets.
- Connect the handset with the RJ-48 socket (10-pin) in the control box.
- Plug in the main power supply. Please make sure that the operating voltage of the system conforms with the local power supply.

### Starting up

**Always reset the lifting system to zero before using for the first time:** Hold down the up-button and the down-button at the same time for 10-30 seconds. The actuators will be moving up and down. If the actuators are not down at the bottom, the actuators will move down. Keep holding the buttons until beeps are heard. The number of beeps depends on the number of actuators/lifting columns (figure A).

**Note:** Before starting up, make sure that all drives/lifters are plugged in completely and correct and that there cannot be a collision while moving down.

**Operating:** Use the “Up” or “Down”-buttons to move the drives.



## Operating Instructions Control Units Type MCB-COMPACT

### Installation (only for authorized personnel)

- Plug in the drives into the 8-pin molex sockets.
- Connect the handset with the 7-pin socket in the control box.
- Plug in the main power supply. Please make sure that the operating voltage of the system conforms with the local power supply.

### Starting up

**Always reset the lifting system to zero before using for the first time:** Make sure the actuators are down at the bottom – hold down-button for 10-30 seconds (figure A). Release down-button (figure B). Hold the down-button in again for 10 seconds until a click is heard (figure C).

**Note:** Before starting up, make sure that all drives/lifters are plugged in completely and correct and that there cannot be a collision while moving down.

**Operating:** Use the “Up” or “Down”-buttons to move the drives.

